

Design and Development of a CPU Scheduler Simulator for Educational Purposes Using SDL

Summary

CPU
Scheduling
Overview

The SDL CPU
Scheduler
Simulator

The CPU
Scheduler
Simulator
Graphical
User Interface

Conclusions
and Further
Work

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- CPU Scheduling Basics
- Related work

2 The SDL CPU Scheduler Simulator

- Requirements
- Behavior Overview
- Simulator structure
- Detailed Behavior

3 The CPU Scheduler Simulator Graphical User Interface

4 Conclusions and Further Work

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CPU Scheduling Basics (I)

- CPU scheduling: deciding which of the ready processes is to be allocated the CPU
- Different selection criteria \Rightarrow different scheduling algorithms
- Two types of scheduling algorithms:
 - one queue algorithms: appropriate when all the processes belong to the same class (same scheduling requirements)
 - multilevel queue algorithms: appropriate for processes belonging to several classes (different scheduling requirements)
- Every algorithm may favor one class of process over another due its properties:
 - performance evaluation parameters (throughput, turnaround time, waiting time, ...) are used for comparing CPU scheduling algorithms

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CPU Scheduling Basics (II)

- Selecting an algorithm appropriate for a process workload
⇒ evaluation of the algorithms based on values of the performance evaluation parameters
 - for example, select the algorithm that produces the least mean waiting time for a process workload
- Several evaluation methods:
 - deterministic modeling: results only valid for the concrete (deterministic) workload used
 - queuing models based: classes of algorithms and statistical distributions of process parameters limited, results not accurate
 - simulation: can support deterministic and statistical based workloads, results can be more accurate than those obtained using queuing models

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CPU Scheduling Basics (III)

- Simulation consist of programming a model of the computer system that behaves like the actual system (at least regarding CPU scheduling) \Rightarrow modeling:
 - arrival, ready and finished queues
 - clock
 - ...
- Design, coding and debugging of a simulator are usually a major task
 - appropriate specification techniques (like SDL) should be used instead of just coding

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Related work and motivation

- Several CPU scheduling simulators have been previously developed: *CPU Scheduling Simulator*, *CPU Scheduler Application*, *Process Scheduling Simulator*, *MOSS Scheduling Simulator* . . .
- Main shortcomings of these simulators:
 - algorithms specific for real-time processes are not supported
 - multilevel queue algorithms are not supported, only single-queue ones
 - deterministic workloads (useful for testing special scenarios) not supported in some of them
- These shortcomings have led to the development of a CPU scheduling simulator using SDL (*sdICPUSched*)

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sdICPUSched: requirements and assumptions

- Main requirements:
 - simulator for educational purposes, mainly used for behavior and performance analysis of CPU scheduling algorithms
 - support for non real-time and real-time algorithms
 - support for multilevel queue algorithms (number of queues, queue algorithm and queue priority can be configured)
- Main assumptions (to simplify the development of the simulator):
 - all the processes characteristics are independent
 - only one CPU burst and zero I/O bursts per process

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sdICPUSched: behavior overview

- Signal-based communication between the simulator and its environment
 - interactions are mainly asynchronous (only synchronous during the phase of simulation configuration)
- Input signals:
 - simulation configuration (algorithm simulated, process parameters. . .)
 - simulation control (start, stop, pause. . .)
- Output signals:
 - confirmation of simulation configuration
 - notification of simulation events (if verbose mode is selected)
 - values of per-process and global statistics
- Scenarios of interactions between the simulator and its environment modeled by MSCs
 - main scenarios: algorithm configuration, process workload configuration and simulation execution

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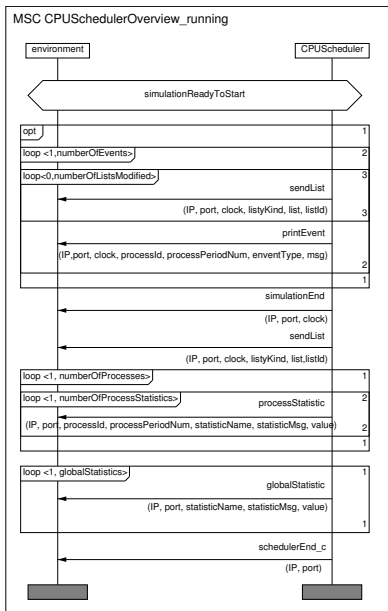
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sdICPUSched: example of an scenario



Simulator structure: motivation issues

- To keep independent intra-queue and inter-queue scheduling functions \Rightarrow two process types:
 - *MasterSchedulerType* for inter-queue scheduling, one instance
 - *SlaveSchedulerType* for intra-queue scheduling, as many instances as ready queues
- To minimize the amount of code not automatically generated from the SDL specification:
 - one simulator program for all the users using the TCP communication module included in the SDL tool
 - programming communication functions with the system environment is avoided
 - no need to use extra coding in C for sending the port number of every instance of the user's simulator program to its GUI (using files, running program parameters, ...)
 - one control process required to route signals of one user to the corresponding scheduling processes

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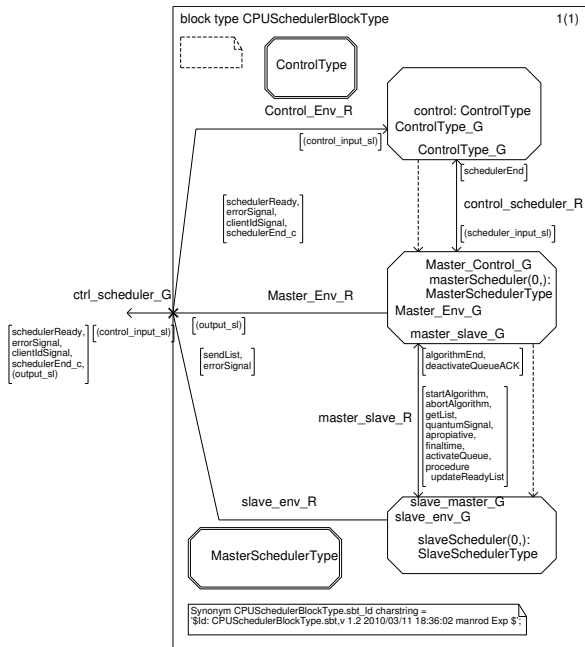
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Simulator structure: CPUSchedulerBlockType



Process Type functions

- `controlType` process type:
 - creating a *masterScheduler* process for a simulation requested by one user
 - dispatching signals coming from different users to the corresponding *masterScheduler* process
- `masterSchedulerType`:
 - simulation configuration
 - inter-queues algorithm (the maximum priority non-empty ready queue is activated)
 - access control of the ready queues shared variables
- `slaveSchedulerType`:
 - simulation of a simple (one ready queue) scheduling algorithm
 - finding process arrivals (storing every arrived process in the ready queue)
 - selecting a process from the ready queue to be executed (leaves the ready queue)
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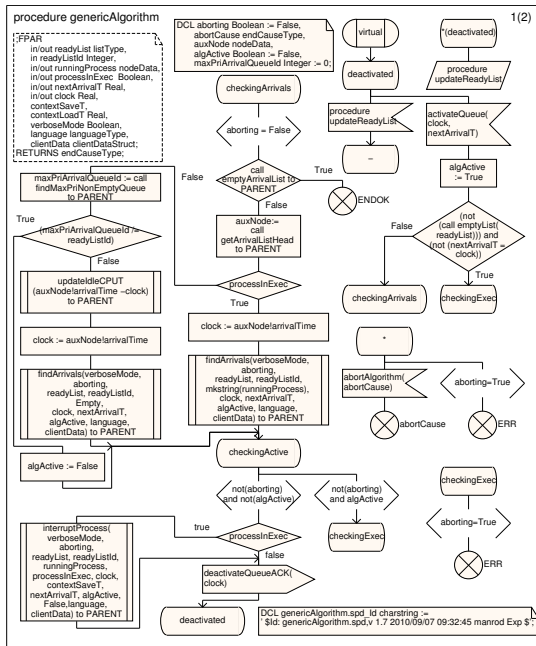
Procedures relating to single-queue algorithms

- Two types of behavior in single queue scheduling algorithms:
 - behavior common to all the algorithms: included in the *genericAlgorithm* procedure
 - algorithm-dependent behavior: included in algorithm specific procedures (one per single-queue algorithm)
- Low level tasks (for example, managing process queues and updating the clock) are specified in auxiliary procedures (*findArrivals*, *executeProcess*, *interruptProcess*, etc.)
 - main behavior of the algorithm is clearly specified without unnecessary low-level details

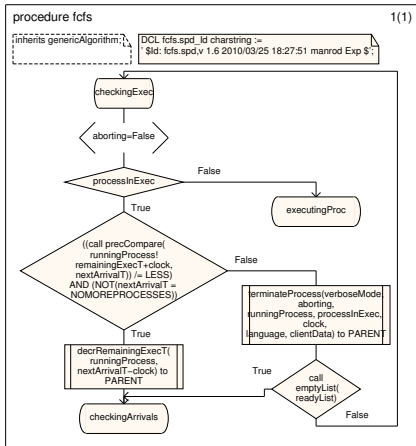
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genericAlgorithm procedure specification (I)



An example of an specific algorithm procedure



The CPU Scheduler Simulator Graphical User Interface: *tkCPUSched*

- A graphical user interface (GUI) has been developed to simplify the access to the simulator functionalities
 - simulator program generated from the SDL specification is only accessible through a TCP socket
- GUI developed using Tcl/Tk language
 - interpreted language that provides rapid development of cross-platform graphical user interfaces
- GUI module for parsing simulator outgoing signals:
 - format of the signals interchanged with the environment: Telelogic ASCII encoding (TCP communications module)
 - example: `{1}{schedulerEnd_c}{{127.0.0.1',50205}}`
 - parsing module based on an automatically generated parser and lexical analyzer
 - parser and lexical analyzer based on a grammar specific to the ASCII encoding: changes in the signal encoding ⇒ modifying the grammar and re-generating the parser and lexical analyzer
 - GUI can be adapted to support a simulator generated by different SDL case tools

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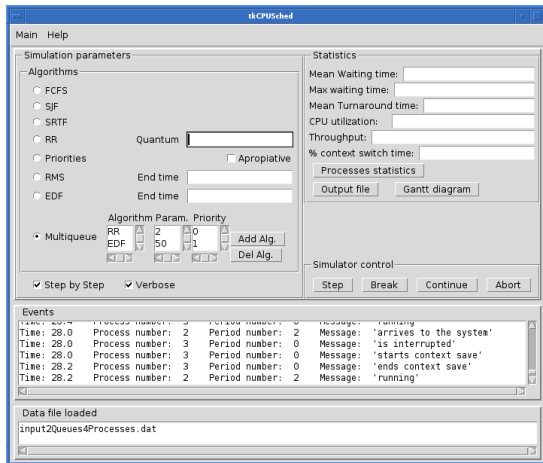
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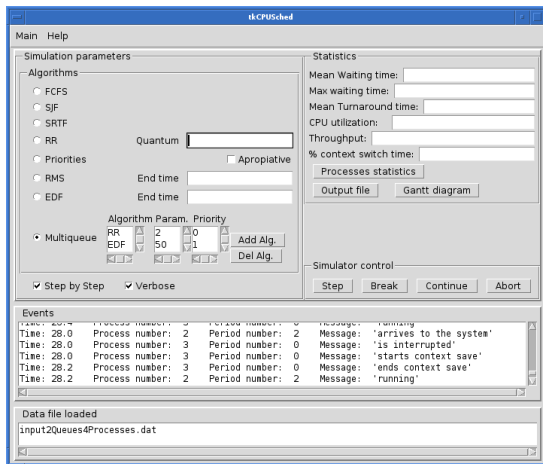
tkCPUSched: main window



- Additional features:

- queue status shown during simulation (and process statistic values)
- plotting of Gantt charts during simulation

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Conclusions (I)

- Simulator features:
 - simulator capable of simulating the behavior of
 - one-queue scheduling algorithms (appropriate for one class of processes workloads)
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 - simulation results (per-process and global statistics) and simulation events shown in a human-readable format using a graphical user interface
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 - powerful testing tools, including tracing of messages exchanged among processes (for example, MSC trace)

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 - support of processes with several CPU and I/O bursts

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Questions?